

UNIVERSITY DEPARTMENTS
ANNA UNIVERSITY : : CHENNAI 600 025
REGULATIONS – 2013
CURRICULUM I TO IV SEMESTERS (FULL TIME)
M.E. POWER SYSTEMS ENGINEERING
SEMESTER I

SL. NO.	COURSE CODE	COURSE TITLE	L	T	P	C
THEORY						
1	PS8101	Advanced Power System Analysis	3	1	0	4
2	PS8102	Power System Operation and Control	3	0	0	3
3	HV8151	Electrical Transients in Power System	3	0	0	3
4	MA8156	Applied Mathematics for Electrical Engineers	3	1	0	4
5	PE8152	Analysis of Electrical Machines	3	0	0	3
6		Elective I	3	0	0	3
PRACTICAL						
7	PS8111	Power System Simulation Laboratory	0	0	3	1
TOTAL			18	2	3	21

SEMESTER II

SL. NO.	COURSE CODE	COURSE TITLE	L	T	P	C
THEORY						
1	PS8201	Advanced Power System Protection	3	0	0	3
2	PS8202	Power System Dynamics	3	0	0	3
3	PS8253	Flexible AC Transmission Systems	3	0	0	3
4	PS8254	Restructured Power System	3	0	0	3
5		Elective II	3	0	0	3
6		Elective III	3	0	0	3
PRACTICAL						
7	PS8211	Advanced Power System Simulation Laboratory	0	0	3	1
8	PS8212	Technical Seminar	0	0	2	1
TOTAL			18	0	5	20

SEMESTER III

SL. NO.	COURSE CODE	COURSE TITLE	L	T	P	C
THEORY						
1	PS8301	Advanced Power System Dynamics	3	0	0	3
2		Elective IV	3	0	0	3
3		Elective V	3	0	0	3
PRACTICAL						
4	PS8311	Project Work Phase I	0	0	12	6
TOTAL			9	0	12	15

SEMESTER IV

SL. NO.	COURSE CODE	COURSE TITLE	L	T	P	C
PRACTICAL						
1	PS8411	Project Work Phase II	0	0	24	12
TOTAL			0	0	24	12

TOTAL NUMBER OF CREDITS = 68

ELECTIVES OF POWER SYSTEMS ENGINEERING

SL. NO.	COURSE CODE	COURSE TITLE	L	T	P	C
THEORY						
1	PS8001	Power System Planning and Reliability	3	0	0	3
2	CO8072	Robust Control	3	0	0	3
3	CO8073	System Identification and Adaptive Control	3	0	0	3
4	CO8074	System Theory	3	0	0	3
5	CO8151	Soft Computing Techniques	3	0	2	4
6	ET8072	MEMS Technology	3	0	0	3
7	ET8152	Microcontroller Based System Design	3	0	0	3
8	ET8351	Distributed Embedded Computing	3	0	0	3
9	HV8071	Applications of High Electric Fields	3	0	0	3
10	HV8251	EHV Power Transmission	3	0	0	3
11	PE8072	Non Linear Dynamics for Power Electronic Circuits	3	0	0	3
12	PE8073	Power Quality	3	0	0	3
13	PE8151	Analysis and Design of Inverters	3	0	0	3
14	PE8351	Power Electronics for Renewable Energy Systems	3	0	0	3
15	HV8073	Design of Substations	3	0	0	3
16	PS8072	Distributed Generation and Micro Grid	3	0	0	3
17	PS8073	Energy Management and Auditing	3	0	0	3
18	PS8074	High Voltage Direct Current Transmission	3	0	0	3
19	PS8075	Optimisation Techniques	3	0	0	3
20	PS8076	Solar and Energy Storage System	3	0	0	3
21	PS8077	Wind Energy Conversion System	3	0	0	3
22	PS8255	Smart Grids	3	0	0	3

UNIVERSITY DEPARTMENTS
ANNA UNIVERSITY CHENNAI: : CHENNAI 600 025
REGULATIONS – 2013
CURRICULUM I TO VI SEMESTERS (PART TIME)
M.E. POWER SYSTEMS ENGINEERING
SEMESTER I

SL. NO.	COURSE CODE	COURSE TITLE	L	T	P	C
THEORY						
1	MA8156	Applied Mathematics for Electrical Engineers	3	1	0	4
2	PS8101	Advanced Power System Analysis	3	1	0	4
3	PS8102	Power System Operation and Control	3	0	0	3
TOTAL			9	2	0	11

SEMESTER II

SL. NO.	COURSE CODE	COURSE TITLE	L	T	P	C
THEORY						
1	PS8201	Advanced Power System Protection	3	0	0	3
2	PS8202	Power System Dynamics	3	0	0	3
3	PS8253	Flexible AC Transmission Systems	3	0	0	3
TOTAL			9	0	0	9

SEMESTER III

SL. NO.	COURSE CODE	COURSE TITLE	L	T	P	C
THEORY						
1	HV8151	Electrical Transients in Power System	3	0	0	3
2	PE8152	Analysis of Electrical Machines	3	0	0	3
3		Elective I	3	0	0	3
PRACTICAL						
4	PS8111	Power System Simulation Laboratory	0	0	3	1
TOTAL			9	0	3	10

SEMESTER IV

SL. NO.	COURSE CODE	COURSE TITLE	L	T	P	C
THEORY						
1	PS8254	Restructured Power System	3	0	0	3
2		Elective II	3	0	0	3
3		Elective III	3	0	0	3
PRACTICAL						
4	PS8211	Advanced Power System Simulation Laboratory	0	0	3	1
5	PS8212	Technical Seminar	0	0	2	1
TOTAL			9	0	5	11

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SEMESTER V

SL. NO.	COURSE CODE	COURSE TITLE	L	T	P	C
THEORY						
1	PS8301	Advanced Power System Dynamics	3	0	0	3
2		Elective IV	3	0	0	3
3		Elective V	3	0	0	3
PRACTICAL						
4	PS8311	Project Work Phase I	0	0	12	6
TOTAL			9	0	12	15

SEMESTER VI

SL. NO.	COURSE CODE	COURSE TITLE	L	T	P	C
PRACTICAL						
1	PS8411	Project Work Phase II	0	0	24	12
TOTAL			0	0	24	12

ELECTIVES OF POWER SYSTEMS ENGINEERING

SL. NO.	COURSE CODE	COURSE TITLE	L	T	P	C
THEORY						
1	PS8001	Power System Planning and Reliability	3	0	0	3
2	CO8072	Robust Control	3	0	0	3
3	CO8073	System Identification and Adaptive Control	3	0	0	3
4	CO8074	System Theory	3	0	0	3
5	CO8151	Soft Computing Techniques	3	0	2	4
6	ET8072	MEMS Technology	3	0	0	3
7	ET8152	Microcontroller Based System Design	3	0	0	3
8	ET8351	Distributed Embedded Computing	3	0	0	3
9	HV8071	Applications of High Electric Fields	3	0	0	3
10	HV8251	EHV Power Transmission	3	0	0	3
11	PE8072	Non Linear Dynamics for Power Electronic Circuits	3	0	0	3
12	PE8073	Power Quality	3	0	0	3
13	PE8151	Analysis and Design of Inverters	3	0	0	3
14	PE8351	Power Electronics for Renewable Energy Systems	3	0	0	3
15	HV8073	Design of Substations	3	0	0	3
16	PS8072	Distributed Generation and Micro Grid	3	0	0	3
17	PS8073	Energy Management and Auditing	3	0	0	3
18	PS8074	High Voltage Direct Current Transmission	3	0	0	3
19	PS8075	Optimisation Techniques	3	0	0	3
20	PS8076	Solar and Energy Storage System	3	0	0	3
21	PS8077	Wind Energy Conversion System	3	0	0	3
22	PS8255	Smart Grids	3	0	0	3

COURSE OBJECTIVES

- To Introduce different techniques of dealing with sparse matrix for large scale power systems.
- To impart in-depth knowledge on different methods of power flow solutions.
- To perform optimal power flow solutions in detail.
- To perform short circuit fault analysis and understand the consequence of different type of faults.
- To Illustrate different numeric al integration methods and factors influencing transient stability

UNIT I SOLUTION TECHNIQUE 9

Sparse Matrix techniques for large scale power systems: Optimal ordering schemes for preserving sparsity. Flexible packed storage scheme for storing matrix as compact arrays – Factorization by Bifactorization and Gauss elimination methods; Repeat solution using Left and Right factors and L and U matrices.

UNIT II POWER FLOW ANALYSIS 9

Power flow equation in real and polar forms; Review of Newton's method for solution; Adjustment of P-V buses; Review of Fast Decoupled Power Flow method; Sensitivity factors for P-V bus adjustment.

UNIT III OPTIMAL POWER FLOW 9

Problem statement; Solution of Optimal Power Flow (OPF) – The gradient method, Newton's method, Linear Sensitivity Analysis; LP methods – With real power variables only – LP method with AC power flow variables and detailed cost functions; Security constrained Optimal Power Flow; Interior point algorithm; Bus Incremental costs.

UNIT IV SHORT CIRCUIT ANALYSIS 9

Formation of bus impedance matrix with mutual coupling (single phase basis and three phase basis) - Computer method for fault analysis using Z_{BUS} and sequence components. Derivation of equations for bus voltages, fault current and line currents, both in sequence and phase – symmetrical and unsymmetrical faults.

UNIT V TRANSIENT STABILITY ANALYSIS 9

Introduction, Numerical Integration Methods: Euler and Fourth Order Runge-Kutta methods, Algorithm for simulation of SMIB and multi-machine system with classical synchronous machine model ; Factors influencing transient stability, Numerical stability and implicit Integration methods.

L:45 +T: 15 TOTAL: 60 PERIODS

TEXTBOOKS

1. G W Stagg , A.H El. Abiad “Computer Methods in Power System Analysis”, McGraw Hill, 1968.
2. P.Kundur, “Power System Stability and Control”, McGraw Hill, 1994.

REFERENCES:

1. A.J.Wood and B.F.Wollenberg,“Power Generation Operation and Control”, John Wiley and sons, New York, 1996.
2. W.F.Tinney and W.S.Meyer, “Solution of Large Sparse System by Ordered Triangular Factorization” IEEE Trans. on Automatic Control, Vol : AC-18, pp:333-346, Aug 1973.
3. K.Zollenkopf, “Bi-Factorization: Basic Computational Algorithm and Programming Techniques ; pp:75-96 ; Book on “Large Sparse Set of Linear Systems” Editor: J.K.Rerd,Academic Press, 1971.
4. M.A.Pai,” Computer Techniques in Power System Analysis”,Tata McGraw-Hill Publishing Company Limited, New Delhi, 2006

PS8102

POWER SYSTEM OPERATION AND CONTROL

L T P C

3 0 0 3

COURSE OBJECTIVES

- To understand the fundamentals of speed governing system and the concept of control areas.
- To provide knowledge about Hydrothermal scheduling, Unit commitment and solution techniques.
- To understand the role of energy control center, SCADA and EMS functions.

UNIT I INTRODUCTION

9

System load variation: System load characteristics, load curves - daily, weekly and annual, load-duration curve, load factor, diversity factor. Reserve requirements: Installed reserves, spinning reserves, cold reserves, hot reserves. Overview of system operation: Load forecasting, techniques of forecasting, basics of power system operation and control.

UNIT II REAL POWER - FREQUENCY CONTROL

9

Fundamentals of speed governing mechanism and modelling: Speed-load characteristics – Load sharing between two synchronous machines in parallel; concept of control area, LFC control of a single-area system: Static and dynamic analysis of uncontrolled and controlled cases, Economic Dispatch Control. Multi-area systems: Two-area system modelling; static analysis, uncontrolled case; tie line with frequency bias control of two-area system derivation, state variable model.

UNIT III HYDROTHERMAL SCHEDULING PROBLEM

9

Hydrothermal scheduling problem: short term and long term-mathematical model, algorithm. Dynamic programming solution methodology for Hydro-thermal scheduling with pumped hydro plant: Optimization with pumped hydro plant-Scheduling of systems

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with pumped hydro plant during off-peak seasons: algorithm. Selection of initial feasible trajectory for pumped hydro plant- Pumped hydro plant as spinning reserve unit-generation of outage induced constraint-Pumped hydro plant as Load management plant.

UNIT IV UNIT COMMITMENT AND ECONOMIC DISPATCH 9

Statement of Unit Commitment (UC) problem; constraints in UC: spinning reserve, thermal unit constraints, hydro constraints, fuel constraints and other constraints; UC solution methods: Priority-list methods, forward dynamic programming approach, numerical problems .Incremental cost curve, co-ordination equations without loss and with loss, solution by direct method and λ -iteration method. Base point and participation factors.-Economic dispatch controller added to LFC control.

UNIT V COMPUTER CONTROL OF POWER SYSTEMS 9

Energy control centre: Functions – Monitoring, data acquisition and control. System hardware configuration – SCADA and EMS functions: Network topology determination, state estimation, security analysis and control. Various operating states: Normal, alert, emergency, in-extremis and restorative-State transition diagram showing various state transitions and control strategies.

TOTAL : 45 PERIODS

TEXTBOOKS

1. Allen.J.Wood and Bruce F.Wollenberg, 'Power Generation, Operation and Control', John Wiley & Sons, Inc., 2003.
2. P. Kundur, 'Power System Stability & Control', McGraw Hill Publications,USA, 1994

REFERENCES:

1. Olle. I. Elgerd, 'Electric Energy Systems Theory – An Introduction', Tata McGraw Hill Publishing Company Ltd,New Delhi, Second Edition, 2003.
2. D.P. Kothari and I.J. Nagrath, 'Modern Power System Analysis', Third Edition, Tata McGraw Hill Publishing Company Limited,New Delhi, 2003.
3. L.L. Grigsby, 'The Electric Power Engineering, Hand Book', CRC Press & IEEE Press, 2001

PROGRESS THROUGH KNOWLEDGE

OBJECTIVES:

- To gain knowledge in the sources and effects of lightning, switching and temporary overvoltages.
- Ability to model and estimate the overvoltages in power system
- To coordinate the insulation of power system and protective devices.
- Ability to model and analyze power system and equipment for transient overvoltages using Electromagnetic Transient Program (EMTP).

UNIT I LIGHTNING OVERVOLTAGES**9**

Mechanism and parameters of lightning flash, protective shadow, striking distance, electrogeometric model for lightning strike, Grounding for protection against lightning – Steady-state and dynamic tower-footing resistance, substation grounding Grid, Direct lightning strokes to overhead lines, without and with shield Wires.

UNIT II SWITCHING AND TEMPORARY OVERVOLTAGES**9**

Switching transients – concept – phenomenon – system performance under switching surges, Temporary overvoltages – load rejection – line faults – ferroresonance, VFTO.

UNIT III TRAVELLING WAVES ON TRANSMISSION LINE**9**

Circuits and distributed constants, wave equation, reflection and refraction – behaviour of travelling waves at the line terminations – Lattice Diagrams – attenuation and distortion – multi-conductor system and multivelocitv waves.

UNIT IV INSULATION CO-ORDINATION**9**

Classification of overvoltages and insulations for insulation co-ordination – Characteristics of protective devices, applications, location of arresters – insulation co-ordination in AIS and GIS.

UNIT V COMPUTATION OF POWER SYSTEM TRANSIENTS**9**

Modelling of power apparatus for transient studies – principles of digital computation – transmission lines, cables, transformer and rotating machines – Electromagnetic Transient program – case studies: line with short and open end, line terminated with R, L, C, transformer, typical power system case study: simulation of possible overvoltages in a high voltage substation.

TOTAL : 45 PERIODS**REFERENCES**

1. Pritindra Chowdhari, "Electromagnetic transients in Power System", John Wiley and Sons Inc., Second Edition, 2009.
2. Allan Greenwood, "Electrical Transients in Power System", Wiley & Sons Inc. New York, 2012.
3. Klaus Ragaller, "Surges in High Voltage Networks", Plenum Press, New York, 1980.
4. Rakosh Das Begamudre, "Extra High Voltage AC Transmission Engineering", (Second edition) Newage International (P) Ltd., New Delhi, 2006.
5. Naidu M S and Kamaraju V, "High Voltage Engineering", Tata McGraw-Hill Publishing Company Ltd., New Delhi, 2004.

6. IEEE Guide for safety in AC substation grounding IEEE Standard 80-2000.
7. Working Group 33/13-09 (1988), 'Very fast transient phenomena associated with Gas Insulated System', CIGRE, 33-13, pp. 1-20.

MA8156 APPLIED MATHEMATICS FOR ELECTRICAL ENGINEERS

**L T P C
3 1 0 4**

OBJECTIVES:

- To develop the ability to apply the concepts of Matrix theory and Linear programming in Electrical Engineering problems.
- To achieve an understanding of the basic concepts of one dimensional random variables and apply in electrical engineering problems.
- To familiarize the students in calculus of variations and solve problems using Fourier transforms associated with engineering applications.

UNIT I MATRIX THEORY (9+3)

The Cholesky decomposition - Generalized Eigen vectors, Canonical basis - QR factorization - Least squares method - Singular value decomposition.

UNIT II CALCULUS OF VARIATIONS (9+3)

Concept of variation and its properties – Euler's equation – Functional dependant on first and higher order derivatives – Functionals dependant on functions of several independent variables – Variational problems with moving boundaries – problems with constraints - Direct methods: Ritz and Kantorovich methods.

UNIT III ONE DIMENSIONAL RANDOM VARIABLES (9+3)

Random variables - Probability function – moments – moment generating functions and their properties – Binomial, Poisson, Geometric, Uniform, Exponential, Gamma and Normal distributions – Function of a Random Variable.

UNIT IV LINEAR PROGRAMMING (9+3)

Formulation – Graphical solution – Simplex method – Two phase method - Transportation and Assignment Models

UNIT V FOURIER SERIES (9+3)

Fourier Trigonometric series: Periodic function as power signals – Convergence of series – Even and odd function: cosine and sine series – Non-periodic function: Extension to other intervals - Power signals: Exponential Fourier series – Parseval's theorem and power spectrum – Eigen value problems and orthogonal functions – Regular Sturm-Liouville systems – Generalized Fourier series.

L:45 +T: 15 TOTAL: 60 PERIODS

BOOKS FOR STUDY:

1. Richard Bronson, "Matrix Operation", Schaum's outline series, 2nd Edition, McGraw Hill, 2011.
2. Gupta, A.S., Calculus of Variations with Applications, Prentice Hall of India Pvt. Ltd., New Delhi, 1997.
3. Oliver C. Ibe, "Fundamentals of Applied Probability and Random Processes, Academic Press, (An imprint of Elsevier), 2010.

4. Taha, H.A., "Operations Research, An introduction", 10th edition, Pearson education, New Delhi, 2010.
5. Andrews L.C. and Phillips R.L., Mathematical Techniques for Engineers and Scientists, Prentice Hall of India Pvt.Ltd., New Delhi, 2005.

REFERENCES:

1. Elsgolts, L., Differential Equations and the Calculus of Variations, MIR Publishers, Moscow, 1973.
2. Grewal, B.S., Higher Engineering Mathematics, 42nd edition, Khanna Publishers, 2012.
3. O'Neil, P.V., Advanced Engineering Mathematics, Thomson Asia Pvt. Ltd., Singapore, 2003.
4. Johnson R. A. and Gupta C. B., "Miller & Freund's Probability and Statistics for Engineers", Pearson Education, Asia, 7th Edition, 2007.

PE8152

ANALYSIS OF ELECTRICAL MACHINES

**LT P C
3 0 0 3**

OBJECTIVES:

- To provide knowledge about the fundamentals of magnetic circuits, energy, force and torque of multi-excited systems.
- To analyze the steady state and dynamic state operation of DC machine through mathematical modeling and simulation in digital computer.
- To provide the knowledge of theory of transformation of three phase variables to two phase variables.
- To analyze the steady state and dynamic state operation of three-phase induction machines using transformation theory based mathematical modeling and digital computer simulation.
- To analyze the steady state and dynamic state operation of three-phase synchronous machines using transformation theory based mathematical modeling and digital computer simulation.

UNIT I PRINCIPLES OF ELECTROMAGNETIC ENERGY CONVERSION 9

Magnetic circuits, permanent magnet, stored magnetic energy, co-energy - force and torque in singly and doubly excited systems – machine windings and air gap mmf - winding inductances and voltage equations.

UNIT II DC MACHINES 9

Elementary DC machine and analysis of steady state operation - Voltage and torque equations – dynamic characteristics of permanent magnet and shunt d.c. motors – Time domain block diagrams - solution of dynamic characteristic by Laplace transformation – digital computer simulation of permanent magnet and shunt d.c. machines.

UNIT III REFERENCE FRAME THEORY 9

Historical background – phase transformation and commutator transformation – transformation of variables from stationary to arbitrary reference frame - variables observed from several frames of reference.

UNIT IV INDUCTION MACHINES**9**

Three phase induction machine, equivalent circuit and analysis of steady state operation – free acceleration characteristics – voltage and torque equations in machine variables and arbitrary reference frame variables – analysis of dynamic performance for load torque variations – digital computer simulation.

UNIT V SYNCHRONOUS MACHINES**9**

Three phase synchronous machine and analysis of steady state operation - voltage and torque equations in machine variables and rotor reference frame variables (Park's equations) – analysis of dynamic performance for load torque variations – digital computer simulation.

TOTAL : 45 PERIODS**TEXT BOOKS**

1. Paul C.Krause, Oleg Wasyzczyk, Scott S, Sudhoff, "Analysis of Electric Machinery and Drive Systems", John Wiley, Second Edition, 2010.

REFERENCES

1. P S Bimbhra, "Generalized Theory of Electrical Machines", Khanna Publishers, 2008.
2. A.E, Fitzgerald, Charles Kingsley, Jr, and Stephan D, Umanx, " Electric Machinery", Tata McGraw Hill, 5th Edition, 1992

PS8111 POWER SYSTEM SIMULATION LABORATORY**L T P C
0 0 3 1****COURSE OBJECTIVES**

- To have hands on experience on various system studies and different techniques used for system planning. software packages.
 - To perform the dynamic analysis of power system
1. Power flow analysis by Newton-Raphson method and Fast decoupled method
 2. Transient stability analysis of single machine-infinite bus system using classical machine model
 3. Contingency analysis: Generator shift factors and line outage distribution factors
 4. Economic dispatch using lambda-iteration method
 5. Unit commitment: Priority-list schemes and dynamic programming
 6. Analysis of switching surge using EMTP : Energisation of a long distributed-parameter line
 7. Analysis of switching surge using EMTP : Computation of transient recovery voltage
 8. Familiarization of Relay Test Kit
 9. Simulation and Implementation of Voltage Source Inverter
 10. Digital Over Current Relay Setting and Relay Coordination.
 11. Co-ordination of over-current and distance relays for radial line protection

TOTAL : 45 PERIODS

COURSE OBJECTIVES

- To illustrate concepts of transformer protection
- To describe about the various schemes of Over current protection
- To analyze distance and carrier protection
- To familiarize the concepts of Busbar protection and Numerical protection

UNIT I EQUIPMENT PROTECTION**9**

Types of transformers – Phasor diagram for a three – Phase transformer-Equivalent circuit of transformer – Types of faults in transformers- Over – current protection Percentage Differential Protection of Transformers - Inrush phenomenon-High resistance Ground Faults in Transformers - Inter-turn faults in transformers - Incipient faults in transformers - Phenomenon of over-fluxing in transformers - Transformer protection application chart .Electrical circuit of the generator –Various faults and abnormal operating conditions-rotor fault –Abnormal operating conditions; numerical examples for typical transformer and generator protection schemes

UNIT II OVER CURRENT PROTECTION**9**

Zones of protection – Primary and Backup protection – operating principles and Relay Construction - Time – Current characteristics-Current setting – Time setting-Over current protective schemes - Reverse power or directional relay - Protection of parallel feeders - Protection of ring feeders - Earth fault and phase fault protection - Combined Earth fault and phase fault protection scheme - Phase fault protective scheme directional earth fault relay - Static over current relays; numerical example for a radial feeder

UNIT III DISTANCE AND CARRIER PROTECTION OF TRANSMISSION LINES**9**

Braw back of over – Current protection – Introduction to distance relay – Simple impedance relay – Reactance relay – mho relays comparison of distance relay – Distance protection of a three – Phase line-reasons for inaccuracy of distance relay reach - Three stepped distance protection - Trip contact configuration for the three - Stepped distance protection - Three-stepped protection of three-phase line against all ten shunt faults - Impedance seen from relay side - Three-stepped protection of double end fed lines-need for carrier – Aided protection – Various options for a carrier –Coupling and trapping the carrier into the desired line section - Unit type carrier aided directional comparison relaying – Carrier aided distance schemes for acceleration of zone II.; numerical example for a typical distance protection scheme for a transmission line.

UNIT IV BUSBAR PROTECTION**9**

Introduction – Differential protection of busbars-external and internal fault - Actual behaviors of a protective CT - Circuit model of a saturated CT - External fault with one CT saturation :need for high impedance – Minimum internal fault that can be detected by the high – Stability ratio of high impedance busbar differential scheme - Supervisory relay-protection of three – Phase busbars-Numerical examples on design of high impedance busbar differential scheme.

UNIT V NUMERICAL PROTECTION

9

Introduction – Block diagram of numerical relay - Sampling theorem- Correlation with a reference wave – Least error squared (LES) technique - Digital filtering-numerical over - Current protection – Numerical transformer differential protection-Numerical distance protection of transmission line

TOTAL : 45 PERIODS

TEXTBOOKS

1. Y.G. Paithankar and S.R Bhide, "Fundamentals of Power System Protection", Prentice-Hall of India, 2003
2. Badri Ram and D.N. Vishwakarma, "Power System Protection and Switchgear", Tata McGraw- Hill Publishing Company, 2002.

REFERENCES

1. P.Kundur, "Power System Stability and Control", McGraw-Hill, 1993.
2. Protective Relaying for Power System II Stanley Horowitz ,IEEE press , New York, 2008
3. T.S.M. Rao, Digital Relay / Numerical relays , Tata McGraw Hill, New Delhi, 1989

PS8202

POWER SYSTEM DYNAMICS

L T P C
3 0 0 3

COURSE OBJECTIVES

- To impart knowledge on dynamic modelling of a synchronous machine in detail
- To describe the modeling of excitation and speed governing system in detail.
- To understand the fundamental concepts of stability of dynamic systems and its classification
- To understand and enhance small signal stability problem of power systems.

UNIT I SYNCHRONOUS MACHINE MODELLING

9

Schematic Diagram, Physical Description: armature and field structure, machines with multiple pole pairs, mmf waveforms, direct and quadrature axes, Mathematical Description of a Synchronous Machine: Basic equations of a synchronous machine: stator circuit equations, stator self, stator mutual and stator to rotor mutual inductances, dq0 Transformation: flux linkage and voltage equations for stator and rotor in dq0 coordinates, electrical power and torque, physical interpretation of dq0 transformation, Per Unit Representations: L_{ad} -reciprocal per unit system and that from power-invariant form of Park's transformation; Equivalent Circuits for direct and quadrature axes, Steady-state Analysis: Voltage, current and flux-linkage relationships, Phasor representation, Rotor angle, Steady-state equivalent circuit, Computation of steady-state values, Equations of Motion: Swing Equation, calculation of inertia constant, Representation in system studies, Synchronous Machine Representation in Stability Studies: Simplifications for large-scale studies : Neglect of stator $p\Psi$ terms and speed

variations, Simplified model with amortisseurs neglected: two-axis model with amortisseur windings neglected, classical model.

UNIT II MODELLING OF EXCITATION AND SPEED GOVERNING SYSTEMS 9

Excitation System Requirements; Elements of an Excitation System; Types of Excitation System; Control and protective functions; IEEE (1992) block diagram for simulation of excitation systems. Turbine and Governing System Modelling: Functional Block Diagram of Power Generation and Control, Schematic of a hydroelectric plant, classical transfer function of a hydraulic turbine (no derivation), special characteristic of hydraulic turbine, electrical analogue of hydraulic turbine, Governor for Hydraulic Turbine: Requirement for a transient droop, Block diagram of governor with transient droop compensation, Steam turbine modelling: Single reheat tandem compounded type only and IEEE block diagram for dynamic simulation; generic speed-governing system model for normal speed/load control function.

UNIT III SMALL-SIGNAL STABILITY ANALYSIS WITHOUT CONTROLLERS 9

Classification of Stability, Basic Concepts and Definitions: Rotor angle stability, The Stability Phenomena. Fundamental Concepts of Stability of Dynamic Systems: State-space representation, stability of dynamic system, Linearisation, Eigen properties of the state matrix: Eigen values and eigenvectors, modal matrices, eigen value and stability, mode shape and participation factor. Single-Machine Infinite Bus (SMIB) Configuration: Classical Machine Model stability analysis with numerical example, Effects of Field Circuit Dynamics: synchronous machine, network and linearised system equations, block diagram representation with K-constants; expression for K-constants (no derivation), effect of field flux variation on system stability: analysis with numerical example.

UNIT IV SMALL-SIGNAL STABILITY ANALYSIS WITH CONTROLLERS 9

Effects Of Excitation System: Equations with definitions of appropriate K-constants and simple thyristor excitation system and AVR, block diagram with the excitation system, analysis of effect of AVR on synchronizing and damping components using a numerical example, Power System Stabiliser: Block diagram with AVR and PSS, Illustration of principle of PSS application with numerical example, Block diagram of PSS with description, system state matrix including PSS, analysis of stability with numerical example. Multi-Machine Configuration: Equations in a common reference frame, equations in individual machine rotor coordinates, illustration of formation of system state matrix for a two-machine system with classical models for synchronous machines, illustration of stability analysis using a numerical example. Principle behind small-signal stability improvement methods: delta-omega and delta P-omega stabilizers.

UNIT V ENHANCEMENT OF SMALL SIGNAL STABILITY 9

Power System Stabilizer – Stabilizer based on shaft speed signal (delta omega) – Delta –P-Omega stabilizer-Frequency-based stabilizers – Digital Stabilizer – Excitation control design – Exciter gain – Phase lead compensation – Stabilizing signal washout stabilizer gain – Stabilizer limits

TOTAL : 45 PERIODS

Attested

Sobhan
DIRECTOR

Centre For Academic Courses
Anna University, Chennai-600 025.

TEXT BOOKS:

1. R.Ramunujam," Power System Dynamics Analysis and Simulation, PHI Learning Private Limited, New Delhi, 2009
2. P. Kundur, "Power System Stability and Control", McGraw-Hill, 1993.

REFERENCES:

1. P. W. Sauer and M. A. Pai," Power System Dynamics and Stability", Stipes Publishing Co, 2007
2. IEEE Committee Report, "Dynamic Models for Steam and Hydro Turbines in Power System Studies", IEEE Trans., Vol.PAS-92, pp 1904-1915, November/December, 1973. on Turbine-Governor Model.
3. P.M Anderson and A.A Fouad, "Power System Control and Stability", Iowa State University Press, Ames, Iowa, 1978.

PS8253**FLEXIBLE AC TRANSMISSION SYSTEMS****L T P C
3 0 0 3****COURSE OBJECTIVES**

- To emphasis the need for FACTS controllers.
- To learn the characteristics, applications and modelling of series and shunt FACTS controllers.
- To analyze the interaction of different FACTS controller and perform control coordination

UNIT I INTRODUCTION**9**

Review of basics of power transmission networks-control of power flow in AC transmission line- Analysis of uncompensated AC Transmission line- Passive reactive power compensation: Effect of series and shunt compensation at the mid-point of the line on power transfer- Need for FACTS controllers- types of FACTS controllers.

UNIT II STATIC VAR COMPENSATOR (SVC)**9**

Configuration of SVC- voltage regulation by SVC- Modelling of SVC for load flow analysis- Modelling of SVC for stability studies-Design of SVC to regulate the mid-point voltage of a SMIB system- Applications: transient stability enhancement and power oscillation damping of SMIB system with SVC connected at the mid-point of the line.

UNIT III THYRISTOR AND GTO THYRISTOR CONTROLLED SERIES CAPACITORS (TCSC and GCSC)**9**

Concepts of Controlled Series Compensation – Operation of TCSC and GCSC- Analysis of TCSC-GCSC – Modelling of TCSC and GCSC for load flow studies- modeling TCSC and GCSC for stability studied- Applications of TCSC and GCSC

UNIT IV VOLTAGE SOURCE CONVERTER BASED FACTS CONTROLLERS 9

Static synchronous compensator(STATCOM)- Static synchronous series compensator(SSSC)- Operation of STATCOM and SSSC-Power flow control with STATCOM and SSSC- Modelling of STATCOM and SSSC for power flow and transient stability studies –operation of Unified and Interline power flow controllers(UPFC and IPFC)- Modelling of UPFC and IPFC for load flow and transient stability studies- Applications.

UNIT V CONTROLLERS AND THEIR COORDINATION 9

FACTS Controller interactions – SVC–SVC interaction - co-ordination of multiple controllers using linear control techniques – Quantitative treatment of control coordination.

TOTAL : 45 PERIODS

TEXT BOOKS

1. Mohan Mathur, R., Rajiv. K. Varma, "Thyristor – Based Facts Controllers for Electrical Transmission Systems", IEEE press and John Wiley & Sons, Inc.
2. K.R.Padiyar," FACTS Controllers in Power Transmission and Distribution", New Age International(P) Ltd., Publishers, New Delhi, Reprint 2008,

REFERENCES:

1. A.T.John, "Flexible AC Transmission System", Institution of Electrical and Electronic Engineers (IEEE), 1999.
2. Narain G.Hingorani, Laszlo. Gyugyl, "Understanding FACTS Concepts and Technology of Flexible AC Transmission System", Standard Publishers, Delhi 2001.
3. V.K.Sood, "HVDC and FACTS controllers- Applications of Static Converters in Power System", 2004, Kluwer Academic Publishers.

PS8254 RESTRICTURED POWER SYSTEM

**L T P C
3 0 0 3**

COURSE OBJECTIVES

- To Introduce the restructuring of power industry and market models.
- To impart knowledge on fundamental concepts of congestion management.
- To analyze the concepts of locational marginal pricing and financial transmission rights.
- To Illustrate about various power sectors in India

UNIT I INTRODUCTION TO RESTRUCTURING OF POWER INDUSTRY 9

Introduction: Deregulation of power industry, Restructuring process, Issues involved in deregulation, Deregulation of various power systems – Fundamentals of Economics: Consumer behavior, Supplier behavior, Market equilibrium, Short and long run costs, Various costs of production – Market models: Market models based on Contractual

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arrangements, Comparison of various market models, Electricity vis – a – vis other commodities, Market architecture, Case study.

UNIT II TRANSMISSION CONGESTION MANAGEMENT

9

Introduction: Definition of Congestion, reasons for transfer capability limitation, Importance of congestion management, Features of congestion management – Classification of congestion management methods – Calculation of ATC - Non – market methods – Market methods – Nodal pricing – Inter zonal and Intra zonal congestion management – Price area congestion management – Capacity alleviation method.

UNIT III LOCATIONAL MARGINAL PRICES AND FINANCIAL TRANSMISSION RIGHTS

9

Mathematical preliminaries: - Locational marginal pricing– Lossless DCOPF model for LMP calculation – Loss compensated DCOPF model for LMP calculation – ACOPF model for LMP calculation – Financial Transmission rights – Risk hedging functionality - Simultaneous feasibility test and revenue adequacy – FTR issuance process: FTR auction, FTR allocation – Treatment of revenue shortfall – Secondary trading of FTRs – Flow gate rights – FTR and market power - FTR and merchant transmission investment.

UNIT IV ANCILLARY SERVICE MANAGEMENT AND PRICING OF TRANSMISSION NETWORK

9

Introduction of ancillary services – Types of Ancillary services – Classification of Ancillary services – Load generation balancing related services – Voltage control and reactive power support devices – Black start capability service - How to obtain ancillary service –Co-optimization of energy and reserve services - International comparison Transmission pricing – Principles – Classification – Rolled in transmission pricing methods – Marginal transmission pricing paradigm – Composite pricing paradigm – Merits and demerits of different paradigm.

UNIT V REFORMS IN INDIAN POWER SECTOR

9

Introduction – Framework of Indian power sector – Reform initiatives - Availability based tariff – Electricity act 2003 – Open access issues – Power exchange – Reforms in the near future

TOTAL : 45 PERIODS

TEXTBOOKS

1. Mohammad Shahidehpour, Muwaffaq Alomoush, Marcel Dekker, “Restructured electrical power systems: operation, trading and volatility” Pub., 2001
2. Kankar Bhattacharya, Jaap E. Daadler, Math H.J. Bollen,” Operation of restructured power systems”, Kluwer Academic Pub., 2001.

REFERENCES

1. Sally Hunt,” Making competition work in electricity”, , John Willey and Sons Inc. 2002
2. Steven Stoft,” Power system economics: designing markets for electricity”, John Wiley & Sons, 2002.

Course objectives

- 1 To analyze the effect of FACTS controllers by performing steady state analysis.
- 2 To have hands on experience on different wind energy conversion technologies.

- 1 Small-signal stability analysis of single machine-infinite bus system using classical machine model
- 2 Small-signal stability analysis of multi-machine configuration with classical machine model
- 3 Induction motor starting analysis
- 4 Load flow analysis of two-bus system with STATCOM
- 5 Transient analysis of two-bus system with STATCOM
- 6 Available Transfer Capability calculation using an existing load flow program
- 7 Study of variable speed wind energy conversion system- DFIG
- 8 Study of variable speed wind energy conversion system- PMSG
- 9 Computation of harmonic indices generated by a rectifier feeding a R-L load
- 10 Design of active filter for mitigating harmonics.

TOTAL: 45 PERIODS

COURSE OBJECTIVES

- To perform transient stability analysis using unified algorithm.
- To impart knowledge on sub-synchronous resonance and oscillations.
- To analyze voltage stability problem in power system.
- To familiarize the methods of transient stability enhancement.

UNIT I TRANSIENT STABILITY ANALYSIS 9

Review of numerical integration methods: Euler and Fourth Order Runge-Kutta methods, Numerical stability and implicit methods, Interfacing of Synchronous machine (variable voltage) model to the transient stability algorithm (TSA) with partitioned – explicit and implicit approaches – Interfacing SVC with TSA-methods to enhance transient stability.

UNIT II UNIFIED ALGORITHM FOR DYNAMIC ANALYSIS OF POWER SYSTEMS 9

Need for unified algorithm- numerical integration algorithmic steps-truncation error-variable step size – handling the discontinuities- numerical stability- application of the algorithm for transient. Mid-term and long-term stability simulations

UNIT III SUBSYNCHRONOUS RESONANCE (SSR) AND OSCILLATIONS 9

Subsynchronous Resonance (SSR) – Types of SSR - Characteristics of series – Compensated transmission systems –Modelling of turbine-generator-trasmission network- Self-excitation due to induction generator effect – Torsional interaction resulting in SSR –Methods of analyzing SSR – Numerical examples illustrating instability of subsynchronous oscillations –time-domain simulation of subsynchronous resonance – EMTP with detailed synchronous machine model- Turbine Generator Torsional Characteristics: Shaft system model – Examples of torsional characteristics – Torsional Interaction with Power System Controls: Interaction with generator excitation controls – Interaction with speed governors – Interaction with nearby DC converters.

UNIT IV TRANSMISSION, GENERATION AND LOAD ASPECTS OF VOLTAGE STABILITY ANALYSIS 9

Review of transmission aspects – Generation Aspects: Review of synchronous machine theory – Voltage and frequency controllers – Limiting devices affecting voltage stability – Voltage-reactive power characteristics of synchronous generators – Capability curves – Effect of machine limitation on deliverable power – Load Aspects – Voltage dependence of loads – Load restoration dynamics – Induction motors – Load tap changers – Thermostatic load recovery – General aggregate load models.

UNIT V ENHANCEMENT OF TRANSIENT STABILITY AND COUNTER MEASURES FOR SUB SYNCHRONOUS RESONANCE [1] 9

Principle behind transient stability enhancement methods: high-speed fault clearing, reduction of transmission system reactance, regulated shunt compensation, dynamic braking, reactor switching, independent pole-operation of circuit-breakers, single-pole switching, fast-valving, high-speed excitation systems; NGH damper scheme.

TOTAL : 45 PERIODS

TEXT BOOKS:

1. R.Ramnujam," Power System Dynamics Analysis and Simulation, PHI Learning Private Limited, New Delhi, 2009
2. T.V. Cutsem and C.Vournas, "Voltage Stability of Electric Power Systems", Kluwer publishers,1998.

REFERENCES

1. P. Kundur, Power System Stability and Control, McGraw-Hill, 1993.
2. H.W. Dommel and N.Sato, "Fast Transient Stability Solutions," IEEE Trans., Vol. PAS-91, pp, 1643-1650, July/August 1972.
3. Roderick J . Frowd and J. C. Giri, "Transient stability and Long term dynamics unified", IEEE Trans., Vol 101, No. 10, October 1982.
4. M.Stubbe, A.Bihain,J.Deuse, J.C.Baader, "A New Unified software program for the study of the dynamic behaviour of electrical power system," IEEE Transaction, Power Systems, Vol.4.No.1,Feb:1989 Pg.129 to 138.

COURSE OBJECTIVES

- To introduces the objectives of Load forecasting.
- To study the fundamentals of Generation system, transmission system and
- Distribution system reliability analysis
- To illustrate the basic concepts of Expansion planning

UNIT I LOAD FORECASTING**9**

Objectives of forecasting - Load growth patterns and their importance in planning - Load forecasting Based on discounted multiple regression technique-Weather sensitive load forecasting-Determination of annual forecasting-Use of AI in load forecasting.

UNIT II GENERATION SYSTEM RELIABILITY ANALYSI**9**

Probabilistic generation and load models- Determination of LOLP and expected value of demand not served –Determination of reliability of iso and interconnected generation systems.

UNIT III TRANSMISSION SYSTEM RELIABILITY ANALYSIS**9**

Deterministic contingency analysis-probabilistic load flow-Fuzzy load flow probabilistic transmission system reliability analysis-Determination of reliability indices like LOLP and expected value of demand not served.

UNIT IV EXPANSION PLANNING**9**

Basic concepts on expansion planning-procedure followed for integrate transmission system planning, current practice in India-Capacitor placer problem in transmission system and radial distributions system.

UNIT V DISTRIBUTION SYSTEM PLANNING OVERVIEW**9**

Introduction, sub transmission lines and distribution substations-Design primary and secondary systems-distribution system protection and coordination of protective devices.

TOTAL: 45 PERIODS**TEXT BOOK:**

1. Reliability Evaluation of Power System - Roy Billinton & Ronald N. Allan, Springer Publication
2. Power System Planning - R.L. Sullivan, Tata McGraw Hill Publishing Company Ltd.

REFERENCES:

1. Modern Power System Planning – X. Wang & J.R. McDonald, McGraw Hill Book Company
2. Electrical Power Distribution Engineering - T. Gönen, McGraw Hill Book Company
3. Generation of Electrical Energy – B.R. Gupta, S. Chand Publications

COURSE OBJECTIVES

- To introduce norms, random spaces and robustness measures
- To educate on H₂ optimal control and estimation techniques
- To educate on H_∞ optimal control techniques
- To educate on the LMI approach of H_∞ control
- To educate on synthesis techniques for robust controllers and illustrate through case studies

UNIT I INTRODUCTION**9**

Norms of vectors and Matrices – Norms of Systems – Calculation of operator Norms – vector Random spaces- Specification for feedback systems – Co-prime factorization and Inner functions –structured and unstructured uncertainty- robustness

UNIT II H₂ OPTIMAL CONTROL**9**

Linear Quadratic Controllers – Characterization of H₂ optimal controllers – H₂ optimal estimation-Kalman Bucy Filter – LQG Controller

UNIT III H-INFINITY OPTIMAL CONTROL-RICCATI APPROACH**9**

Formulation – Characterization of H-infinity sub-optimal controllers by means of Riccati equations – H-infinity control with full information – H_∞ estimation

UNIT IV H-INFINITY OPTIMAL CONTROL- LMI APPROACH**9**

Formulation – Characterization of H-infinity sub-optimal controllers by means of LMI Approach – Properties of H-infinity sub-optimal controllers – H-infinity synthesis with pole-placement constraints

UNIT V SYNTHESIS OF ROBUST CONTROLLERS & CASE STUDIES**9**

Synthesis of Robust Controllers – Small Gain Theorem – D-K –iteration- Control of Inverted Pendulum- Control of CSTR – Control of Aircraft – Robust Control of Second-order Plant- Robust Control of Distillation Column

TOTAL : 45 PERIODS**REFERENCES**

1. U. Mackenroth “Robust Control Systems: Theory and Case Studies”, Springer International Edition, 2010.
2. J.B. Burl, “ Linear optimal control H₂ and H-infinity methods”, Addison W Wesley, 1998
3. D. Xue, Y.Q. Chen, D. P. Atherton, "Linear Feedback Control Analysis and Design with MATLAB, Advances In Design and Control", Society for Industrial and Applied Mathematics, 2007.
4. I. R. Petersen, V.A. Ugrinovskii and A. V. Savkin, “Robust Control Design using H-infinity Methods”, Springer, 2000.
5. M. J. Grimble, “Robust Industrial Control Systems: Optimal Design Approach for Polynomial Systems”, John Wiley and Sons Ltd., Publication, 2006.

COURSE OBJECTIVES

- To introduce various model structures for system identification
- To impart knowledge on parametric and non-parametric identification
- To introduce non-linear identification techniques
- To introduce the concept of adaptation techniques and control
- To illustrate the identification and adaptive control techniques through
- case studies

UNIT I MODELS FOR IDENTIFICATION 9

Models of LTI systems: Linear Models-State space Models-OE model- Model sets, Structures and Identifiability-Models for Time-varying and Non-linear systems: Models with Nonlinearities – Non-linear state-space models-Black box models, Fuzzy models'.

UNIT II NON-PARAMETRIC AND PARAMETRIC IDENTIFICATION 9

Transient response and Correlation Analysis – Frequency response analysis – Spectral Analysis – Least Square – Recursive Least Square –Forgetting factor- Maximum Likelihood – Instrumental Variable methods.

UNIT III NON-LINEAR IDENTIFICATION 9

Open and closed loop identification: Approaches – Direct and indirect identification – Joint input-output identification – Non-linear system identification – Wiener models – Power series expansions - State estimation techniques – Non linear identification using Neural Network and Fuzzy Logic.

UNIT IV ADAPTIVE CONTROL AND ADAPTATION TECHNIQUES 9

Introduction – Uses – Auto tuning – Self Tuning Regulators (STR) – Model Reference Adaptive Control (MRAC) – Types of STR and MRAC – Different approaches to self-tuning regulators – Stochastic Adaptive control – Gain Scheduling.

UNIT V CASE STUDIES 9

Inverted Pendulum, Robot arm, process control application: heat exchanger, Distillation column, application to power system, Ship steering control.

TOTAL : 45 PERIODS**REFERENCES**

1. Ljung," System Identification Theory for the User", PHI, 1987.
2. Torsten Soderstrom, Petre Stoica, "System Identification", prentice Hall `International (UK) Ltd,1989.
4. Astrom and Wittenmark," Adaptive Control ", PHI
5. William S. Levine, " Control Hand Book".
6. Narendra and Annasamy," Stable Adaptive Control Systems, Prentice Hall, 1989.

COURSE OBJECTIVES

- To educate on modeling and representing systems in state variable form
- To educate on solving linear and non-linear state equations
- To illustrate the role of controllability and observability
- To educate on stability analysis of systems using Lyapunov's theory
- To educate on modal concepts and design of state and output feedback controllers and estimators

UNIT I STATE VARIABLE REPRESENTATION 9

Introduction-Concept of State-State equation for Dynamic Systems -Time invariance and linearity- Non uniqueness of state model-State Diagrams - Physical System and State Assignment.

UNIT II SOLUTION OF STATE EQUATIONS 9

Existence and uniqueness of solutions to Continuous-time state equations-Solution of Nonlinear and Linear Time Varying State equations-Evaluation of matrix exponential-System modes- Role of Eigenvalues and Eigenvectors.

UNIT III CONTROLLABILITY AND OBSERVABILITY 9

Controllability and Observability-Stabilizability and Detectability-Test for Continuous time Systems- Time varying and Time invariant case-Output Controllability-Reducibility-System Realizations.

UNIT IV STABILITY 9

Introduction-Equilibrium Points-Stability in the sense of Lyapunov-BIBO Stability-Stability of LTI Systems-Equilibrium Stability of Nonlinear Continuous Time Autonomous Systems-The Direct Method of Lyapunov and the Linear Continuous-Time Autonomous Systems-Finding Lyapunov Functions for Nonlinear Continuous Time Autonomous Systems-Krasovskii and Variable-Gradient Method.

UNIT V MODAL CONTROL 9

Introduction-Controllable and Observable Companion Forms-SISO and MIMO Systems-The Effect of State Feedback on Controllability and Observability-Pole Placement by State Feedback for both SISO and MIMO Systems-Full Order and Reduced Order Observers.

TOTAL : 45 PERIODS**REFERENCES:**

1. M. Gopal, "Modern Control System Theory", New Age International, 2005.
2. K. Ogatta, "Modern Control Engineering", PHI, 2002.
3. John S. Bay, "Fundamentals of Linear State Space Systems", McGraw-Hill, 1999.
4. D. Roy Choudhury, "Modern Control Systems", New Age International, 2005.
5. John J. D'Azzo, C. H. Houpis and S. N. Sheldon, "Linear Control System Analysis and Design with MATLAB", Taylor Francis, 2003.
6. Z. Bubnicki, "Modern Control Theory", Springer, 2005.

PROGRAM OBJECTIVES

- To review the fundamentals of ANN and fuzzy set theory
- To make the students understand the use of ANN for modeling and control of non-linear system and to get familiarized with the ANN tool box.
- To impart knowledge of using Fuzzy logic for modeling and control of non-linear systems and get familiarized with the FLC tool box.
- To make the students to understand the use of optimization techniques.
- To familiarize the students on various hybrid control schemes, P.S.O and get familiarized with the ANFIS tool box.

UNIT I OVERVIEW OF ARTIFICIAL NEURAL NETWORK (ANN) & FUZZY LOGIC 9

Review of fundamentals - Biological neuron, Artificial neuron, Activation function, Single Layer Perceptron – Limitations – Multi Layer Perceptron – Back propagation algorithm (BPA); Fuzzy set theory – Fuzzy sets – Operation on Fuzzy sets - Scalar cardinality, fuzzy cardinality, union and intersection, complement (yager and sugeno), equilibrium points, aggregation, projection, composition, decomposition, cylindrical extension, fuzzy relation – Fuzzy membership functions.

UNIT II NEURAL NETWORKS FOR MODELLING AND CONTROL 9

Modeling of non linear systems using ANN- NARX, NNSS, NARMAX - Generation of training data - optimal architecture – Model validation- Control of non linear system using ANN- Direct and Indirect neuro control schemes- Adaptive neuro controller – Case study - Familiarization of Neural Network Control Tool Box.

UNIT III FUZZY LOGIC FOR MODELLING AND CONTROL 9

Modeling of non linear systems using fuzzy models(Mamdani and Sugeno) –TSK model - Fuzzy Logic controller – Fuzzification – Knowledge base – Decision making logic – Defuzzification- Adaptive fuzzy systems- Case study - Familiarization of Fuzzy Logic Tool Box.

UNIT IV GENETIC ALGORITHM 9

Basic concept of Genetic algorithm and detail algorithmic steps, adjustment of free parameters. Solution of typical control problems using genetic algorithm. Concept on some other search techniques like Tabu search, Ant-colony search and Particle Swarm Optimization.

UNIT V HYBRID CONTROL SCHEMES 9

Fuzzification and rule base using ANN–Neuro fuzzy systems-ANFIS –Optimization of membership function and rule base using Genetic Algorithm and Particle Swarm Optimization - Case study–Introduction to Support Vector Regression – Familiarization of ANFIS Tool Box.

TOTAL : 45+30 = 75 PERIODS**Soft Computing Techniques - Lab**

To implement adaline and madaline with bipolar inputs and outputs using NN toolbox.

To implement back propagation for a given input pattern using NN toolbox.

To implement discrete hopfield network and test for given input pattern using NN toolbox.

To implement fuzzy set operation and properties using FUZZY toolbox.

To perform max-min composition of two matrices obtained from Cartesian product using 'm file' in MATLAB.

Write a program to verify the various laws associated with fuzzy set using FUZZY toolbox.

Write a matlab program for maximizing $f(x) = x^2$ using GA, where x is ranges from 0 to 31 (Perform only 5 iterations). Find the objective function and 'x' value.
 Design FLC for a FOPDT process using FUZZY toolbox.
 Design a Neuro model for an inverted pendulum using NN toolbox.
 Design Fuzzy model for an inverted pendulum using FUZZY toolbox.

REFERENCES

1. Laurene V.Fausett, "Fundamentals of Neural Networks, Architecture, Algorithms, and Applications", Pearson Education, 2008.
2. Timothy J.Ross, "Fuzzy Logic with Engineering Applications", Wiley, Third Edition, 2010.
3. George J.Klir and Bo Yuan, "Fuzzy Sets and Fuzzy Logic: Theory and Applications", Prentice Hall, First Edition, 1995.
4. David E.Goldberg, "Genetic Algorithms in Search, Optimization, and Machine Learning", Pearson Education, 2009.
5. W.T.Miller, R.S.Sutton and P.J.Webrose, "Neural Networks for Control", MIT Press, 1996.
6. C.Cortes and V.Vapnik, "Support-Vector Networks, Machine Learning", 1995.

ET8072

MEMS TECHNOLOGY

**LT P C
3 0 0 3**

Pre-requisites: Basic Instrumentation ,Material Science,Programming

COURSE OBJECTIVES

- To teach the students properties of materials ,microstructure and fabrication methods.
- To teach the design and modeling of Electrostatic sensors and actuators.
- To teach the characterizing thermal sensors and actuators through design and modeling
- To teach the fundamentals of piezoelectric sensors and actuators
- To give exposure to different MEMS and NEMS devices.

UNIT I MEMS:MICRO-FABRICATION, MATERIALS AND ELECTRO-MECHANICAL CONCEPTS 9

Overview of micro fabrication – Silicon and other material based fabrication processes – Concepts: Conductivity of semiconductors-Crystal planes and orientation-stress and strain-flexural beam bending analysis-torsional deflections-Intrinsic stress- resonant frequency and quality factor.

UNIT II ELECTROSTATIC SENSORS AND ACTUATION 9

Principle, material, design and fabrication of parallel plate capacitors as electrostatic sensors and actuators-Applications

UNIT III THERMAL SENSING AND ACTUATION 9

Principle, material, design and fabrication of thermal couples, thermal bimorph sensors, thermal resistor sensors-Applications.

UNIT IV PIEZOELECTRIC SENSING AND ACTUATION **9**
Piezoelectric effect-cantilever piezo electric actuator model-properties of piezoelectric materials-Applications.

UNIT V CASE STUDIES **9**
Piezoresistive sensors, Magnetic actuation, Micro fluidics applications, Medical applications, Optical MEMS.-NEMS Devices

TOTAL : 45 PERIODS

REFERENCES

1. Chang Liu, "Foundations of MEMS", Pearson International Edition, 2006.
2. Marc Madou , "Fundamentals of microfabrication",CRC Press, 1997.
3. Boston , "Micromachined Transducers Sourcebook",WCB McGraw Hill, 1998.
4. M.H.Bao "Micromechanical transducers :Pressure sensors, accelerometers and gyroscopes", Elsevier, Newyork, 2000.

ET8152 MICROCONTROLLER BASED SYSTEM DESIGN **LT P C**
3 0 0 3

Pre-requisites: Basics of Processor Architecture & Programming in 8085/8051

COURSE OBJECTIVES

- To expose the students to the fundamentals of microcontroller based system design.
- To teach I/O and RTOS role on microcontroller.
- To impart knowledge on
- PIC Microcontroller based system design.
- To introduce Microchip PIC 8 bit peripheral system Design
- To give case study experiences for microcontroller based applications.

UNIT I 8051 ARCHITECTURE **9**
Architecture – memory organization – addressing modes – instruction set – Timers - Interrupts - I/O ports, Interfacing I/O Devices – Serial Communication.

UNIT II 8051 PROGRAMMING **9**
Assembly language programming – Arithmetic Instructions – Logical Instructions –Single bit Instructions – Timer Counter Programming – Serial Communication Programming Interrupt Programming – RTOS for 8051 – RTOSLite – FullRTOS – Task creation and run – LCD digital clock/thermometer using FullRTOS

UNIT III PIC MICROCONTROLLER **9**
Architecture – memory organization – addressing modes – instruction set – PIC programming in Assembly & C –I/O port, Data Conversion, RAM & ROM Allocation, Timer programming, MP-LAB.

UNIT IV PERIPHERAL OF PIC MICROCONTROLLER 9
Timers – Interrupts, I/O ports- I2C bus-A/D converter-UART- CCP modules -ADC, DAC and Sensor Interfacing –Flash and EEPROM memories.

UNIT V SYSTEM DESIGN – CASE STUDY 9
Interfacing LCD Display – Keypad Interfacing - Generation of Gate signals for converters and Inverters - Motor Control – Controlling DC/ AC appliances – Measurement of frequency - Stand alone Data Acquisition System.

TOTAL : 45 PERIODS

REFERENCES:

1. Muhammad Ali Mazidi, Rolin D. Mckinlay, Danny Causey ‘ PIC Microcontroller and Embedded Systems using Assembly and C for PIC18’, Pearson Education 2008
2. John Iovine, ‘PIC Microcontroller Project Book ’, McGraw Hill 2000
3. Myke Predko, “Programming and customizing the 8051 microcontroller”, Tata McGraw Hill 2001.
4. Muhammad Ali Mazidi, Janice G. Mazidi and Rolin D. McKinlay, ‘The 8051 Microcontroller and Embedded Systems’ Prentice Hall, 2005.

**ET8351 DISTRIBUTED EMBEDDED COMPUTING LT P C
3 0 0 3**

Pre-requisites: Basics in Programming, Embedded System & operating systems

OBJECTIVES

- To expose the students to the fundamentals of Network communication technologies.
- To teach the fundamentals of Internet
- To study on Java based Networking
- To introduce network routing Agents
- To study the basis for network on-chip technologies

UNIT I THE HARDWARE INFRASTRUCTURE 9
Broad Band Transmission facilities – Open Interconnection standards –Local Area Networks – Wide Area Networks – Network management – Network Security – Cluster computers.

UNIT II INTERNET CONCEPTS 9
Capabilities and limitations of the internet – Interfacing Internet server applications to corporate databases HTML and XML Web page design and the use of active components.

UNIT III DISTRIBUTED COMPUTING USING JAVA 9
IO streaming – Object serialization – Networking – Threading – RMI – multicasting – distributed databases – embedded java concepts – case studies.

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UNIT IV EMBEDDED AGENT**9**

Introduction to the embedded agents – Embedded agent design criteria – Behaviour based, Functionality based embedded agents – Agent co-ordination mechanisms and benchmarks embedded-agent. Case study: Mobile robots.

UNIT V EMBEDDED COMPUTING ARCHITECTURE**9**

Synthesis of the information technologies of distributed embedded systems – analog/digital co-design – optimizing functional distribution in complex system design – validation and fast prototyping of multiprocessor system-on-chip – a new dynamic scheduling algorithm for real-time multiprocessor systems.

TOTAL : 45 PERIODS**REFERENCES:**

1. Dietel & Dietel, "JAVA how to program", Prentice Hall 1999.
2. Sape Mullender, "Distributed Systems", Addison-Wesley, 1993.
3. George Coulouris and Jean Dollimore, "Distributed Systems – concepts and design", Addison –Wesley 1988.
4. "Architecture and Design of Distributed Embedded Systems", edited by Bernd Kleinjohann C-lab, Universitat Paderborn, Germany, Kluwer AcademicPub, Boston, April 2001, 248 pp.

HV8071 APPLICATIONS OF HIGH ELECTRIC FIELDS**LT PC
3 0 0 3****OBJECTIVE:**

To impart knowledge on,

- different HV applications in industry and food preservation.
- different HV applications in cancer treatments and microbial inactivation.
- the awareness on safety and hazard issues.

UNIT I APPLICATION IN INDUSTRY**9**

Introduction – electrostatic applications- electrostatic precipitation, separation , painting / coating, spraying ,imaging ,printing ,Transport of materials – Sandpaper Manufacture – Smoke particle detector – Electrostatic spinning ,pumping , propulsion – Ozone generation – Biomedical applications.

UNIT II APPLICATION IN MICROBIAL INACTIVATION**9**

Introduction-definitions, descriptions and applications-mechanisms of microbial in-activations-electrical breakdown-electroporation-inactivation models -Critical factors-analysis of process, product and microbial factors-pulse generators and treatment chamber design-Research needs.

UNIT III APPLICATION IN FOOD PRESERVATION**9**

Processing of juices, milk, egg, meat and fish products- Processing of water and waste – Industrial feasibility, cost and efficiency analysis.

UNIT IV APPLICATION IN CANCER TREATMENT**9**

Different types of cancer – Different types of treatments, anti-cancer drugs – Electro-chemotherapy – Electric fields in cancer tissues – Modeling, analysis of cancer tissues.

UNIT V SAFETY AND ELECTROSTATIC HAZARDS**9**

Introduction – Nature of static electricity – Triboelectric series – Basic laws of Electrostatic electricity– materials and static electricity – Electrostatic discharges (ESD) – Static electricity problems – Hazards of Electrostatic electricity in industry – Hazards from electrical equipment and installations – Static eliminators and charge neutralizers – Lightning protection.

TOTAL : 45 PERIODS**REFERENCES**

1. N.H.Malik, A.A.Ai-Arainy, M.I.Qureshi, “Electrical Insulation in power systems”, Marcel Dekker, inc., 1998.
2. Mazen Abdel-Salam, Hussien Anis, Ahdab El-Morshedy, “High Voltage Engineering”, Second Edition, Theory and Practice, Marcel Dekker, Inc. 2000,
3. John D.Kraus, Daniel A.Fleisch, “Electromagnetics with Applications” McGraw Hill International Editions, 1992.
4. Shoaib Khan, “ Industrial Power System”, CRC Press, Taylor & Francis group, 2008.
5. G.V. Barbosa –Canovas , “Pulsed electric fields in food processing:Fundamental aspects and applications” CRC Publisher Edition March 1 2001.
6. H L M Lelieveld and Notermans.S,et.al., “Food preservation by pulsed electric fields: From research to application”, Woodhead Publishing Ltd. October 2007.

HV8251**EHV POWER TRANSMISSION****L T P C
3 0 0 3****OBJECTIVES:**

To impart knowledge on,

- various parameters and voltage gradients of transmission line conductors.
- effect of electric fields and various losses on EHV transmission line due to corona effects
- the design requirements of EHV AC and DC lines.

UNIT I INTRODUCTION**9**

Standard transmission voltages – different configurations of EHV and UHV lines – average values of line parameters – power handling capacity and line loss – costs of transmission lines and equipment – mechanical considerations in line performance.

UNIT II CALCULATION OF LINE PARAMETERS**9**

Calculation of resistance, inductance and capacitance for multi-conductor lines – calculation of sequence inductances and capacitances – line parameters for different modes of propagation – resistance and inductance of ground return.

UNIT III VOLTAGE GRADIENTS OF CONDUCTORS

9

Charge-potential relations for multi-conductor lines – surface voltage gradient on conductors – gradient factors and their use – distribution of voltage gradient on sub conductors of bundle - voltage gradients on conductors in the presence of ground wires on towers.

UNIT IV CORONA EFFECTS

9

Power losses and audible losses: I^2R loss and corona loss - audible noise generation and characteristics - limits for audible noise - Day-Night equivalent noise level- radio interference: corona pulse generation and properties - limits for radio interference fields.

UNIT V ELECTROSTATIC FIELD AND DESIGN OF EHV LINES

9

Effect of EHV line on heavy vehicles - calculation of electrostatic field of AC lines- effect of high field on humans, animals, and plants - measurement of electrostatic fields - electrostatic Induction in unenergised circuit of a D/C line - induced voltages in insulated ground wires - electromagnetic interference, Design of EHV lines.

TOTAL : 45 PERIODS

REFERENCES

1. Rakosh Das Begamudre, "Extra High Voltage AC Transmission Engineering", Second Edition, New Age International Pvt. Ltd., 2006.
2. Pritindra Chowdhari, "Electromagnetic transients in Power System", John Wiley and Sons Inc., 2009.
3. Power Engineer's Handbook, Revised and Enlarged 6th Edition, TNEB Engineers' Association, October 2002.
4. Sunil S.Rao, "EHV-AC, HVDC Transmission & Distribution Engineering", Third Edition, Khanna Publishers, 2008.

PE8072 NON LINEAR DYNAMICS FOR POWER ELECTRONIC CIRCUITS L T P C

3 0 0 3

OBJECTIVES :

- To understand the non linear behavior of power electronic converters.
- To understand the techniques for investigation on non linear behavior of power electronic converters.
- To analyse the non linear phenomena in DC to DC converters.
- To analyse the non linear phenomena in AC and DC Drives.
- To introduce the control techniques for control of non linear behavior in power electronic systems.

UNIT I BASICS OF NONLINEAR DYNAMICS

9

Basics of Nonlinear Dynamics: System, state and state space model, Vector field-Modeling of Linear, nonlinear and Linearized systems, Attractors , chaos, Poincare map, Dynamics of Discrete time system, Lyapunov Exponent, Bifurcations, Bifurcations of

smooth map, Bifurcations in piece wise smooth maps, border crossing and border collision bifurcation.

UNIT II TECHNIQUES FOR INVESTIGATION OF NONLINEAR PHENOMENA 9

Techniques for experimental investigation, Techniques for numerical investigation, Computation of averages under chaos, Computations of spectral peaks, Computation of the bifurcation and analyzing stability.

UNIT III NONLINEAR PHENOMENA IN DC-DC CONVERTERS 9

Border collision in the Current Mode controlled Boost Converter, Bifurcation and chaos in the Voltage controlled Buck Converter with latch, Bifurcation and chaos in the Voltage controlled Buck Converter without latch, Bifurcation and chaos in Cuk Converter. Nonlinear phenomenon in the inverter under tolerance band control

UNIT IV NONLINEAR PHENOMENA IN DRIVES 9

Nonlinear Phenomenon in Current controlled and voltage controlled DC Drives, Nonlinear Phenomenon in PMSM Drives.

UNIT V CONTROL OF CHAOS 9

Hysteresis control, Sliding mode and switching surface control, OGY Method, Pyragas method, Time Delay control. Application of the techniques to the Power electronics circuit and drives.

TOTAL : 45 PERIODS

TEXT BOOKS:

1. George C. Vargheese, July 2001 Wiley – IEEE Press S Banerjee, Nonlinear Phenomena in Power Electronics, IEEE Press
2. Steven H Strogatz, Nonlinear Dynamics and Chaos, Westview Press
3. C.K.TSE Complex Behaviour of Switching Power Converters, CRC Press, 2003

PE8073

POWER QUALITY

**LT P C
3 0 0 3**

OBJECTIVES :

- To understand the various power quality issues.
- To understand the concept of power and power factor in single phase and three phase systems supplying non linear loads
- To understand the conventional compensation techniques used for power factor correction and load voltage regulation.
- To understand the active compensation techniques used for power factor correction.
- To understand the active compensation techniques used for load voltage regulation.

UNIT I INTRODUCTION 9

Introduction – Characterisation of Electric Power Quality: Transients, short duration and long duration voltage variations, Voltage imbalance, waveform distortion, Voltage fluctuations, Power frequency variation, Power acceptability curves – power quality problems: poor load power factor, Non linear and unbalanced loads, DC offset in loads, Notching in load voltage, Disturbance in supply voltage – Power quality standards.

Attested

Sobhan
DIRECTOR

Centre For Academic Courses
Anna University, Chennai-600 025.

UNIT II ANALYSIS OF SINGLE PHASE AND THREE PHASE SYSTEM 9

Single phase linear and non linear loads – single phase sinusoidal, non sinusoidal source – supplying linear and nonlinear load – three phase Balance system – three phase unbalanced system – three phase unbalanced and distorted source supplying non linear loads – concept of pf – three phase three wire – three phase four wire system.

UNIT III CONVENTIONAL LOAD COMPENSATION METHODS 9

Principle of load compensation and voltage regulation – classical load balancing problem : open loop balancing – closed loop balancing, current balancing – harmonic reduction and voltage sag reduction – analysis of unbalance – instantaneous of real and reactive powers – Extraction of fundamental sequence component from measured.

UNIT IV LOAD COMPENSATION USING DSTATCOM 9

Compensating single – phase loads – Ideal three phase shunt compensator structure – generating reference currents using instantaneous PQ theory – Instantaneous symmetrical components theory – Generating reference currents when the source is unbalanced – Realization and control of DSTATCOM – DSTATCOM in Voltage control mode

UNIT V SERIES COMPENSATION OF POWER DISTRIBUTION SYSTEM 9

Rectifier supported DVR – Dc Capacitor supported DVR – DVR Structure – voltage Restoration – Series Active Filter – Unified power quality conditioner.

TOTAL : 45 PERIODS

TEXT BOOKS

1. Arindam Ghosh “Power Quality Enhancement Using Custom Power Devices”, Kluwer Academic Publishers, 2002
2. G.T.Heydt, “Electric Power Quality”, Stars in a Circle Publications, 1994(2nd edition)
3. Power Quality - R.C. Duggan
4. Power system harmonics –A.J. Arrillaga
5. Power Electronic Converter Harmonics –Derek A. Paice

PROGRESS THROUGH KNOWLEDGE

OBJECTIVES :

- To Provide the electrical circuit concepts behind the different working modes of inverters so as to enable deep understanding of their operation.
- To equip with required skills to derive the criteria for the design of power converters for UPS, Drives etc.,
- Ability to analyse and comprehend the various operating modes of different configurations of power converters.
- Ability to design different single phase and three phase inverters.

UNIT I SINGLE PHASE INVERTERS**12**

Introduction to self commutated switches : MOSFET and IGBT - Principle of operation of half and full bridge inverters – Performance parameters – Voltage control of single phase inverters using various PWM techniques – various harmonic elimination techniques – forced commutated Thyristor inverters – Design of UPS

UNIT II THREE PHASE VOLTAGE SOURCE INVERTERS**9**

180 degree and 120 degree conduction mode inverters with star and delta connected loads – voltage control of three phase inverters: single, multi pulse, sinusoidal, space vector modulation techniques – Application to drive system

UNIT III CURRENT SOURCE INVERTERS**9**

Operation of six-step thyristor inverter – inverter operation modes – load – commutated inverters – Auto sequential current source inverter (ASCI) – current pulsations – comparison of current source inverter and voltage source inverters – PWM techniques for current source inverters.

UNIT IV MULTILEVEL & BOOST INVERTERS**9**

Multilevel concept – diode clamped – flying capacitor – cascade type multilevel inverters - Comparison of multilevel inverters - application of multilevel inverters – PWM techniques for MLI – Single phase & Three phase Impedance source inverters .

UNIT V RESONANT INVERTERS**6**

Series and parallel resonant inverters - voltage control of resonant inverters – Class E resonant inverter – resonant DC – link inverters.

TOTAL : 45 PERIODS**TEXT BOOKS**

1. Rashid M.H., "Power Electronics Circuits, Devices and Applications ", Prentice Hall India, Third Edition, New Delhi, 2004.
2. Jai P.Agrawal, "Power Electronics Systems", Pearson Education, Second Edition, 2002.
3. Bimal K.Bose "Modern Power Electronics and AC Drives", Pearson Education, Second Edition, 2003.
4. Ned Mohan, T.M Undeland and W.P Robbin, "Power Electronics: converters, Application and design" John Wiley and sons. Wiley India edition, 2006.
5. Philip T. krein, "Elements of Power Electronics" Oxford University Press -1998.

REFERENCES

1. P.C. Sen, "Modern Power Electronics", Wheeler Publishing Co, First Edition, New Delhi, 1998.
2. P.S.Bimbra, "Power Electronics", Khanna Publishers, Eleventh Edition, 2003.

PE8351 POWER ELECTRONICS FOR RENEWABLE ENERGY SYSTEMS **L T P C**
3 0 0 3

OBJECTIVES :

- To Provide knowledge about the stand alone and grid connected renewable energy systems.
- To equip with required skills to derive the criteria for the design of power converters for renewable energy applications.
- To analyse and comprehend the various operating modes of wind electrical generators and solar energy systems.
- To design different power converters namely AC to DC, DC to DC and AC to AC converters for renewable energy systems.
- To develop maximum power point tracking algorithms.

UNIT I INTRODUCTION 9

Environmental aspects of electric energy conversion: impacts of renewable energy generation on environment (cost-GHG Emission) - Qualitative study of different renewable energy resources ocean, Biomass, Hydrogen energy systems : operating principles and characteristics of: Solar PV, Fuel cells, wind electrical systems-control strategy, operating area.

UNIT II ELECTRICAL MACHINES FOR RENEWABLE ENERGY CONVERSION 9

Review of reference theory fundamentals-principle of operation and analysis: IG, PMSG, SCIG and DFIG.

UNIT III POWER CONVERTERS 9

Solar: Block diagram of solar photo voltaic system : line commutated converters (inversion-mode) - Boost and buck-boost converters- selection Of inverter, battery sizing, array sizing.

Wind: three phase AC voltage controllers- AC-DC-AC converters: uncontrolled rectifiers, PWM Inverters, Grid Interactive Inverters-matrix converters.

UNIT IV ANALYSIS OF WIND AND PV SYSTEMS 9

Stand alone operation of fixed and variable speed wind energy conversion systems and solar system-Grid connection Issues -Grid integrated PMSG and SCIG Based WECS- Grid Integrated solar system

UNIT V HYBRID RENEWABLE ENERGY SYSTEMS**9**

Need for Hybrid Systems- Range and type of Hybrid systems- Case studies of Wind-PV- Maximum Power Point Tracking (MPPT).

TOTAL : 45 PERIODS**TEXT BOOK**

1. S.N.Bhadra, D. Kastha, & S. Banerjee "Wind Electrical Systems", Oxford University Press, 2009

REFERENCES:

1. Rashid .M. H "power electronics Hand book", Academic press, 2001.
2. Rai. G.D, "Non conventional energy sources", Khanna publishes, 1993.
3. Rai. G.D," Solar energy utilization", Khanna publishes, 1993.
4. Gray, L. Johnson, "Wind energy system", prentice hall linc, 1995.
5. Non-conventional Energy sources B.H.Khan Tata McGraw-hill Publishing Company, New Delhi.

HV8073**DESIGN OF SUBSTATIONS****LT P C
3 0 0 3****OBJECTIVES:**

- To provide in-depth knowledge on design criteria of Air Insulated Substation (AIS) and Gas Insulated Substation (GIS).
- To study the substation insulation co-ordination and protection scheme.
- To study the source and effect of fast transients in AIS and GIS.

UNIT I INTRODUCTION TO AIS AND GIS**9**

Introduction – characteristics – comparison of Air Insulated Substation (AIS) and Gas Insulated Substation (GIS) – main features of substations, Environmental considerations, Planning and installation.

UNIT II MAJOR EQUIPMENT AND LAYOUT OF AIS AND GIS**9**

Major equipment – design features – equipment specification, types of electrical stresses, mechanical aspects of substation design.

UNIT III INSULATION COORDINATION OF AIS AND GIS**9**

Introduction – stress at the equipment – insulation strength and its selection – standard BILs – Application of simplified method – Comparison with IEEE and IEC guides.

UNIT IV GROUNDING AND SHIELDING**9**

Definitions – soil resistivity measurement – ground fault currents – ground conductor – design of substation grounding system – shielding of substations – Shielding by wires and masts.

UNIT V FAST TRANSIENTS PHENOMENON IN AIS AND GIS**9**

Introduction – Disconnector switching in relation to very fast transients – origin of VFTO – propagation and mechanism of VFTO – VFTO characteristics – Effects of VFTO.

*Attested**Sobhan*
DIRECTOR

Centre For Academic Courses
Anna University, Chennai-600 025.

REFERENCES

1. Andrew R. Hileman, "Insulation coordination for power systems", Taylor and Francis, 1999.
2. M.S. Naidu, "Gas Insulation Substations", I.K. International Publishing House Private Limited, 2008.
3. Klaus Ragallar, "Surges in high voltage networks" Plenum Press, New York, 1980. "Power Engineer's handbook", TNEB Association.
4. Pritindra Chowdhuri, "Electromagnetic transients in power systems", PHI Learning Private Limited, New Delhi, Second edition, 2004.
5. "Design guide for rural substation", United States Department of Agriculture, RUS Bulletin, 1724E-300, June 2001.

PS8072

DISTRIBUTED GENERATION AND MICRO GRID

**L T P C
3 0 0 3**

OBJECTIVES

- To illustrate the concept of distributed generation
- To analyze the impact of grid integration.
- To study concept of Microgrid and its configuration

UNIT I

INTRODUCTION

9

Conventional power generation: advantages and disadvantages, Energy crises, Non-conventional energy (NCE) resources: review of Solar PV, Wind Energy systems, Fuel Cells, micro-turbines, biomass, and tidal sources.

UNIT II

DISTRIBUTED GENERATIONS (DG)

9

Concept of distributed generations, topologies, selection of sources, regulatory standards/ framework, Standards for interconnecting Distributed resources to electric power systems: IEEE 1547. DG installation classes, security issues in DG implementations. Energy storage elements: Batteries, ultra-capacitors, flywheels. Captive power plants

UNIT III

IMPACT OF GRID INTEGRATION

9

Requirements for grid interconnection, limits on operational parameters, voltage, frequency, THD, response to grid abnormal operating conditions, islanding issues. Impact of grid integration with NCE sources on existing power system: reliability, stability and power quality issues.

UNIT IV

BASICS OF A MICROGRID

9

Concept and definition of microgrid, microgrid drivers and benefits, review of sources of microgrids, typical structure and configuration of a microgrid, AC and DC microgrids, Power Electronics interfaces in DC and AC microgrids,

UNIT V CONTROL AND OPERATION OF MICROGRID**9**

Modes of operation and control of microgrid: grid connected and islanded mode, Active and reactive power control, protection issues, anti-islanding schemes: passive, active and communication based techniques, microgrid communication infrastructure, Power quality issues in microgrids, regulatory standards, Microgrid economics, Introduction to smart microgrids.

TOTAL : 45 PERIODS**REFERENCES**

1. "Voltage Source Converters in Power Systems: Modeling, Control and Applications", Amirnaser Yazdani, and Reza Iravani, IEEE John Wiley Publications.
2. "Power Switching Converters: Medium and High Power", Dorin Neacsu, CRC Press, Taylor & Francis, 2006.
3. "Solar Photo Voltaics", Chetan Singh Solanki, PHI learning Pvt. Ltd., New Delhi, 2009
4. "Wind Energy Explained, theory design and applications," J.F. Manwell, J.G. McGowan Wiley publication
5. "Biomass Regenerable Energy", D. D. Hall and R. P. Grover, John Wiley, New York, 1987.
6. "Renewable Energy Resources" John Twidell and Tony Weir, Taylor and Francis Publications, Second edition.

PS8073 ENERGY MANAGEMENT AND AUDITING**LT PC
3 0 0 3****COURSE OBJECTIVES**

- To study the concepts behind economic analysis and Load management.
- To emphasize the energy management on various electrical equipments and metering.
- To illustrate the concept of lighting systems and cogeneration.

UNIT I INTRODUCTION**9**

Need for energy management - energy basics- designing and starting an energy management program – energy accounting -energy monitoring, targeting and reporting- energy audit process.

UNIT II ENERGY COST AND LOAD MANAGEMENT**9**

Important concepts in an economic analysis - Economic models-Time value of money-Utility rate structures- cost of electricity-Loss evaluation
Load management: Demand control techniques-Utility monitoring and control system-HVAC and energy management-Economic justification

UNIT III ENERGY MANAGEMENT FOR MOTORS, SYSTEMS, AND ELECTRICAL EQUIPMENT**9**

Systems and equipment- Electric motors-Transformers and reactors-Capacitors and synchronous machines

UNIT IV METERING FOR ENERGY MANAGEMENT 9
Relationships between parameters-Units of measure-Typical cost factors- Utility meters - Timing of meter disc for kilowatt measurement - Demand meters - Paralleling of current transformers - Instrument transformer burdens-Multitasking solid-state meters - Metering location vs. requirements- Metering techniques and practical examples

UNIT V LIGHTING SYSTEMS & COGENERATION 9
Concept of lighting systems - The task and the working space -Light sources - Ballasts - Luminaries - Lighting controls-Optimizing lighting energy - Power factor and effect of harmonics on power quality - Cost analysis techniques-Lighting and energy standards
Cogeneration: Forms of cogeneration - feasibility of cogeneration- Electrical interconnection.

TOTAL: 45 PERIODS

TEXT BOOKS

1. Barney L. Capehart, Wayne C. Turner, and William J. Kennedy, Guide to Energy Management, Fifth Edition, The Fairmont Press, Inc., 2006
2. Eastop T.D & Croft D.R, Energy Efficiency for Engineers and Technologists., Logman Scientific & Technical, ISBN-0-582-03184, 1990.

REFERENCES

1. Reay D.A, Industrial Energy Conservation, 1st edition, Pergamon Press, 1977.
2. IEEE Recommended Practice for Energy Management in Industrial and Commercial Facilities, IEEE, 196.
3. Amit K. Tyagi, Handbook on Energy Audits and Management, TERI, 2003.

**PS8074 HIGH VOLTAGE DIRECT CURRENT TRANSMISSION L T P C
3 0 0 3**

COURSE OBJECTIVES

- To impart knowledge on operation, modelling and control of HVDC link.
- To perform steady state analysis of AC/DC system.
- To expose various HVDC simulators.

UNIT I DC POWER TRANSMISSION TECHNOLOGY 6
Introduction - Comparison of AC and DC transmission – Application of DC transmission – Description of DC transmission system - Planning for HVDC transmission – Modern trends in DC transmission – DC breakers – Cables, VSC based HVDC.

UNIT II ANALYSIS OF HVDC CONVERTERS AND HVDC SYSTEM CONTROL 12
Pulse number, choice of converter configuration – Simplified analysis of Graetz circuit - Converter bridge characteristics – characteristics of a twelve pulse converter- detailed analysis of converters.

General principles of DC link control – Converter control characteristics – System control hierarchy - Firing angle control – Current and extinction angle control – Generation of harmonics and filtering - power control – Higher level controllers.

UNIT III MULTITERMINAL DC SYSTEMS 9

Introduction – Potential applications of MTDC systems - Types of MTDC systems - Control and protection of MTDC systems - Study of MTDC systems.

UNIT IV POWER FLOW ANALYSIS IN AC/DC SYSTEMS 9

Per unit system for DC Quantities - Modelling of DC links - Solution of DC load flow - Solution of AC-DC power flow – Unified, Sequential and Substitution of power injection method.

UNIT V SIMULATION OF HVDC SYSTEMS 9

Introduction – DC LINK Modelling , Converter Modeling and State Space Analysis , Philosophy and tools – HVDC system simulation, Online and OFFline simulators — Dynamic interactions between DC and AC systems.

TOTAL: 45 PERIODS

TEXT BOOKS

1. P. Kundur, “Power System Stability and Control”, McGraw-Hill, 1993
2. K.R.Padiyar, , “HVDC Power Transmission Systems”, New Age International (P) Ltd., New Delhi, 2002.

REFERENCES

1. J.Arrillaga, , “High Voltage Direct Current Transmission”, Peter Pregrinus, London, 1983.
2. Erich Uhlmann, “ Power Transmission by Direct Current”, BS Publications, 2004.
3. V.K.Sood,HVDC and FACTS controllers – Applications of Static Converters in Power System, APRIL 2004 , Kluwer Academic Publishers.

PS8075

OPTIMISATION TECHNIQUES

**L T P C
3 0 0 3**

COURSE OBJECTIVES

- To introduce the different optimization problems and techniques
- To study the fundamentals of the linear and non-linear programming problem.
- To understand the concept of dynamic programming and genetic algorithm technique

UNIT I INTRODUCTION 9

Definition, Classification of optimization problems, Classical Optimization Techniques, Single and Multiple Optimization with and without inequality constraints.

UNIT II LINEAR PROGRAMMING (LP) 9

Simplex method of solving LPP, revised simplex method, duality, Constrained optimization, Theorems and procedure, Linear programming, mathematical model, solution technique, duality.

Attested

Sobhan
DIRECTOR

Centre For Academic Courses
Anna University, Chennai-600 025.

UNIT IV ENERGY STORAGE SYSTEMS 9
Impact of intermittent generation – Battery energy storage – solar thermal energy storage – pumped hydroelectric energy storage

UNIT V APPLICATIONS 9
Water pumping – battery chargers – solar car – direct-drive applications –Space – Telecommunications.

TOTAL : 45 PERIODS

TEXT BOOKS:

1. Eduardo Lorenzo G. Araujo, Solar electricity engineering of photovoltaic systems, Progensa,1994.
2. Stuart R.Wenham, Martin A.Green, Muriel E. Watt and Richard Corkish, Applied Photovoltaics, 2007,Earthscan, UK.

REFERENCES:

1. Frank S. Barnes & Jonah G. Levine, Large Energy storage Systems Handbook , CRC Press, 2011.
2. Solar & Wind energy Technologies – McNeils, Frenkel, Desai, Wiley Eastern, 1990
3. Solar Energy – S.P. Sukhatme, Tata McGraw Hill,1987.

**PS8077 WIND ENERGY CONVERSION SYSTEM LT P C
3 0 0 3**

COURSE OBJECTIVES

- To learn the design and control principles of Wind turbine.
- To understand the concepts of fixed speed and variable speed, wind energy conversion systems.
- To analyze the grid integration issues.

UNIT I INTRODUCTION 9
Components of WECS-WECS schemes-Power obtained from wind-simple momentum theory-Power coefficient-Sabinin's theory-Aerodynamics of Wind turbine

UNIT II WIND TURBINES 9
HAWT-VAWT-Power developed-Thrust-Efficiency-Rotor selection-Rotor design considerations-Tip speed ratio-No. of Blades-Blade profile-Power Regulation-yaw control-Pitch angle control-stall control-Schemes for maximum power extraction.

UNIT III FIXED SPEED SYSTEMS 9
Generating Systems- Constant speed constant frequency systems -Choice of Generators-Deciding factors-Synchronous Generator-Squirrel Cage Induction Generator- Model of Wind Speed- Model wind turbine rotor - Drive Train model-Generator model for Steady state and Transient stability analysis.

UNIT IV VARIABLE SPEED SYSTEMS 9
Need of variable speed systems-Power-wind speed characteristics-Variable speed constant frequency systems synchronous generator- DFIG- PMSG -Variable speed generators modeling - Variable speed variable frequency schemes.

UNIT V GRID CONNECTED SYSTEMS

9

Wind interconnection requirements, low-voltage ride through (LVRT), ramp rate limitations, and supply of ancillary services for frequency and voltage control, current practices and industry trends wind interconnection impact on steady-state and dynamic performance of the power system including modeling issue.

TOTAL: 45 PERIODS

TEXT BOOKS

1. L.L.Freris "Wind Energy conversion Systems", Prentice Hall, 1990
2. S.N.Bhadra, D.Kastha,S.Banerjee,"Wind Electrical Sytems",Oxford University Press,2010.

REFERENCES

1. Ion Boldea, "Variable speed generators", Taylor & Francis group, 2006.
2. E.W.Golding "The generation of Electricity by wind power", Redwood burn Ltd., Trowbridge,1976.
3. N. Jenkins," Wind Energy Technology" John Wiley & Sons,1997
4. S.Heir "Grid Integration of WECS", Wiley 1998.

PS8255

SMART GRIDS

**LT P C
3 0 0 3**

COURSE OBJECTIVES

- To Study about Smart Grid technologies, different smart meters and advanced metering infrastructure.
- To familiarize the power quality management issues in Smart Grid.
- To familiarize the high performance computing for Smart Grid applications

UNIT I INTRODUCTION TO SMART GRID

9

Evolution of Electric Grid, Concept, Definitions and Need for Smart Grid, Smart grid drivers, functions, opportunities, challenges and benefits, Difference between conventional & Smart Grid, Concept of Resilient & Self Healing Grid, Present development & International policies in Smart Grid, Diverse perspectives from experts and global Smart Grid initiatives.

UNIT II SMART GRID TECHNOLOGIES

9

Technology Drivers, Smart energy resources,Smart substations, Substation Automation, Feeder Automation ,Transmission systems: EMS, FACTS and HVDC, Wide area monitoring, Protection and control, Distribution systems: DMS, Volt/VAr control,Fault Detection, Isolation and service restoration, Outage management,High-Efficiency Distribution Transformers, Phase Shifting Transformers, Plug in Hybrid Electric Vehicles (PHEV).

UNIT III SMART METERS AND ADVANCED METERING INFRASTRUCTURE

9

Introduction to Smart Meters, Advanced Metering infrastructure (AMI) drivers and benefits,AMI protocols, standards and initiatives, AMI needs in the smart grid, Phasor

Measurement Unit(PMU), Intelligent Electronic Devices(IED) & their application for monitoring & protection.

UNIT IV POWER QUALITY MANAGEMENT IN SMART GRID 9
Power Quality & EMC in Smart Grid, Power Quality issues of Grid connected Renewable Energy Sources, Power Quality Conditioners for Smart Grid, Web based Power Quality monitoring, Power Quality Audit.

UNIT V HIGH PERFORMANCE COMPUTING FOR SMART GRID APPLICATIONS 9
Local Area Network (LAN), House Area Network (HAN), Wide Area Network (WAN), Broadband over Power line (BPL), IP based Protocols, Basics of Web Service and CLOUD Computing to make Smart Grids smarter, Cyber Security for Smart Grid.

TOTAL : 45 PERIODS

TEXT BOOKS :

1. Stuart Borlase "Smart Grid :Infrastructure, Technology and Solutions",CRC Press 2012.
2. Janaka Ekanayake, Nick Jenkins, KithsiriLiyanage, Jianzhong Wu, Akihiko Yokoyama, "Smart Grid: Technology and Applications", Wiley.

REFERENCES:

1. Vehbi C. Güngör, DilanSahin, TaskinKocak, Salih Ergüt, Concettina Buccella, Carlo Cecati, and Gerhard P. Hancke, Smart Grid Technologies: Communication Technologies and Standards IEEE Transactions On Industrial Informatics, Vol. 7, No. 4, November 2011.
2. Xi Fang, Satyajayant Misra, Guoliang Xue, and Dejun Yang "Smart Grid – The New and Improved Power Grid: A Survey" , IEEE Transaction on Smart Grids,

